## NC STATE UNIVERSITY

# Curvature of Light Responsive, Shape Memory Polymers for the Production of Biologically-Inspired, Functional Devices









### Hypothesis and Goals

- Global curvature is dependent upon sample geometry, ink distribution, and ink density.
- Controlled global curvature will allow for the production of functional, strong devices.
  - Finite element modeling provides a predictive tool for bio-inspired and functional devices.





Direct Mechanism for Out-of-Plane Deformation



### **Bio-Inspired Structures**

Three-dimensional point clouds confirm excellent qualitative agreement between computational and experimental results.





### Functional Grippers



Structures have been shown to maintain > 17,000x their own mass!

### Conclusions

- 1. Ink density and distribution directly impacts light absorbance, final degree of folding, and onset time of folding.
- 2. Global curvature control is achieved by manipulation of aspect ratio and distribution of shrinkage.
- 3. Functional devices, such as grippers, are generated demonstrating applicability and overall strength of materials.
- Excellent qualitative and quantitative agreement between experimental and computational outcomes demonstrate the predictive capabilities of our system.

### Future Work

- Perform a systematic study to determine the impact of sample geometry, ink distribution, and ink density upon the strength of functional grippers.
- Determine critical features required for Golden Spiral production.
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- Determine the critical inked surface area coverage required for two-step curvature.
- Generate and optimize the production of spherical objects.

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1. Randall et. al., Trends in Biotech., 2012

- 2. Images from WWW
- 3. Liu et. al., Soft Matter, 2011
- 4. Hubbard & Mailen et. al., Soft Matter, 2017

